

Technical Report: Sparse Doubly-Selective Channel Estimation Techniques for OSTBC MIMO-OFDM Systems: A Hierarchical Bayesian Kalman Filter Based Approach

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I. COMPLEXITY ANALYSIS

The per EM complexity for each block of the proposed P-HBKF and D-HBKF schemes are determined as follows. Table I presents the complexities of the various steps in the P-HBKF scheme for estimation of the sparse channel \mathbf{h}_n using the Algorithm 1 described in the manuscript. The complexities of the various intermediate steps in the joint estimation of the sparse channel \mathbf{h}_n and data detection $\hat{\mathbf{a}}_{k,n}^{(i)}(m)$ in the D-HBKF technique are similarly given in Table II. The dominant terms in each Table are presented in red color.

TABLE I: Computational Complexity of P-HBKF Technique

Steps in P-HBKF	Multiplications	Additions
Computation of $\widehat{\mathbf{y}}_{\mathcal{P},n n-1}$ using Eq.(73)	$LN_R N_T + N_P N_c N_R^3 L^2 N_T^2$	$N_P N_c N_R^3 L^2 N_T^2 - N_P N_c N_R^2 L N_T$
Computation of $\mathbf{y}_{\mathcal{P},e,n}$ using Eq.(76)	—	$N_P N_c N_R$
Computation of $\Sigma_n^{(i)}$ in E-Step	$L^2 N_R^3 N_T^2 N_P N_c + \frac{1}{2} L^3 N_R^3 N_T^3$ $+ \frac{3}{2} L^2 N_R^2 N_T^2 + LN_R N_T$	$L^2 N_R^3 N_T^2 N_P N_c + \frac{1}{2} L^3 N_R^3 N_T^3$ $- \frac{3}{2} L^2 N_R^2 N_T^2 + LN_R N_T$
Computation of $\mu_n^{(i)}$ in E-Step	$L^2 N_R^3 N_T^2 N_P N_c + LN_R^2 N_T N_P N_c$	$L^2 N_R^3 N_T^2 N_P N_c - LN_R N_T$
Computation of $\widehat{\Gamma}_n^{(i)}$ in M-Step	$LN_R N_T + 2L$	$2LN_R N_T - 2L$
Computation of $\mathbf{M}_{n n-1}$ using Eq.(74)	$L^2 N_R^2 N_T^2 + LN_R N_T$	$LN_R N_T$
Computation of \mathbf{K}_n using Eq.(75)	$2N_P N_c N_R^3 L^2 N_T^2 + 2N_P^2 N_c^2 N_R^3 L N_T$	$2N_P N_c N_R^3 L^2 N_T^2 - 2N_P N_c N_R^2 L N_T$ $2N_P^2 N_c^2 N_R^3 L N_T - LN_T N_P N_c N_R^2$ $N_P N_c N_R - N_P^2 N_c^2 N_R^2$
Computation of $\widehat{\mathbf{h}}_{n n}$ using Eq.(77)	$LN_R^2 N_T N_P N_c$	$LN_R^2 N_T N_P N_c$
Computation of $\mathbf{M}_{n n}$ using Eq.(78)	$L^2 N_R^3 N_T^2 N_P N_c + L^3 N_R^3 N_T^3$	$L^2 N_R^3 N_T^2 N_P N_c + L^3 N_R^3 N_T^3$ $LN_R N_T - 2L^2 N_R^2 N_T^2$

TABLE II: Computational Complexity of D-HBKF Technique

Steps in D-HBKF	Multiplications	Additions
Computation of $\widehat{\mathbf{y}}_{\mathcal{B},n n-1}$ using Eq.(73)	$LN_R N_T + KNN_c N_R^3 L^2 N_T^2$	$KNN_c N_R^3 L^2 N_T^2 - KNN_c N_R^2 LN_T$
Computation of $\mathbf{y}_{\mathcal{B},e,n}$ using Eq.(76)	–	$KNN_c N_R$
Computation of $\Sigma_{\mathcal{B},n}^{(i)}$ in E-Step	$L^2 N_R^3 N_T^2 KNN_c + \frac{1}{2} L^3 N_R^3 N_T^3$ $+ \frac{3}{2} L^2 N_R^2 N_T^2 + LN_R N_T$	$L^2 N_R^3 N_T^2 KNN_c + \frac{1}{2} L^3 N_R^3 N_T^3$ $- \frac{3}{2} L^2 N_R^2 N_T^2 + LN_R N_T$
Computation of $\mu_{\mathcal{B},n}^{(i)}$ in E-Step	$L^2 N_R^3 N_T^2 KNN_c + LN_R^2 N_T KNN_c$	$L^2 N_R^3 N_T^2 KNN_c - LN_R N_T$
Computation of $\widehat{\mathbf{I}}_n^{(i)}$ in M-Step	$LN_R N_T + 2L$	$2LN_R N_T - 2L$
Computation of $\mathbf{M}_{n n-1}^{(i)}$ using Eq.(74)	$L^2 N_R^2 N_T^2 + LN_R N_T$	$LN_R N_T$
Computation of $\mathbf{K}_n^{(i)}$ using Eq.(75)	$2KNN_c N_R^3 L^2 N_T^2 + 2K^2 N^2 N_c^3 N_R^3 LN_T$	$2KNN_c N_R^3 L^2 N_T^2 - 2KNN_c N_R^2 LN_T$ $2K^2 N^2 N_c^3 N_R^3 LN_T - LN_T KNN_c N_R^2$ $KNN_c N_R - K^2 N^2 N_c^2 N_R^2$
Computation of $\widehat{\mathbf{h}}_{n n}^{(i)}$ using Eq.(77)	$LN_R^2 N_T KNN_c$	$LN_R^2 N_T KNN_c$
Computation of $\mathbf{M}_{n n}^{(i)}$ using Eq.(78)	$L^2 N_R^3 N_T^2 KNN_c + L^3 N_R^3 N_T^3$	$L^2 N_R^3 N_T^2 KNN_c + L^3 N_R^3 N_T^3$ $LN_R N_T - 2L^2 N_R^2 N_T^2$
Computation of $\widehat{\mathcal{H}}_n^{(i)}$ using Eq.(64)	$NN_R N_T L$	$NN_T N_R (L - 1)$
Computation of $\widetilde{\mathbf{M}}_n^{(i)}$ in Eq.(72)	$N_T^3 N_R^3 N L^2 + N_T^3 N_R^3 N^2 L$	$N_R^3 N_T^3 L^2 N + N_T^3 N_R^3 N^2 L$ $- N_R^2 N_T^2 LN - N_R^2 N_T^2 N^2$
Computation of $\zeta_n^{(i)}(m)$ using Eq.(72)	$N_T N_R N$	$2N_T N_R N - 2N$
Computation of $\mathcal{C}_n(m)$ using Eq.(65)	$2N_R N_T N_c N_s N$	$2N_R N_T N_c N_s N + 2N_R N_c N_s N$
Computation of $\widehat{\mathbf{a}}_{k,n}^{(i)}(m)$ using Eq.(71)	$2N_s N_R N_c K N + 2N_s K N$	$2N_s N_R N_c K N - 2N_s K N$

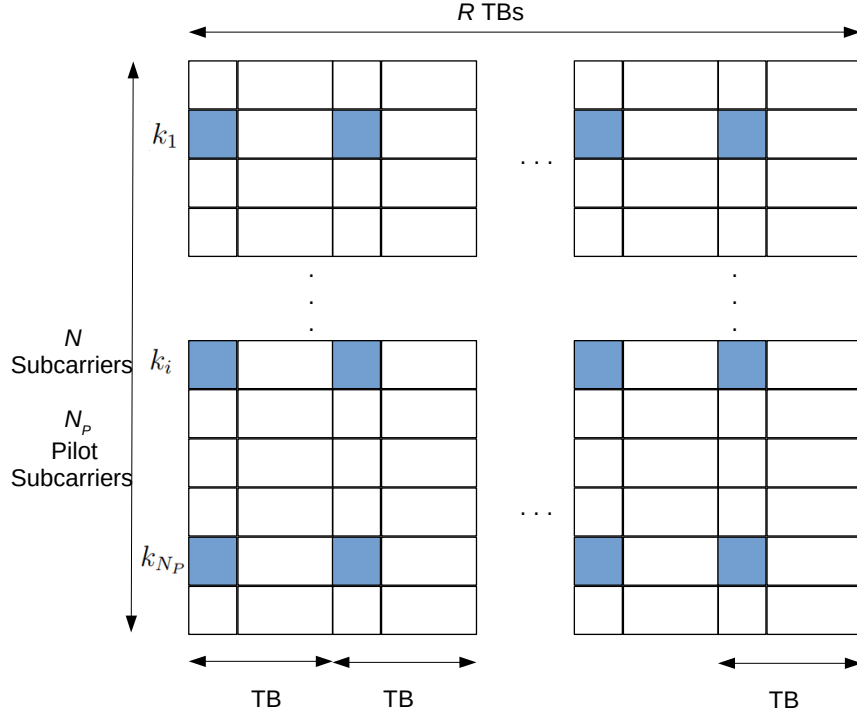


Fig. 1: Pilot pattern for the proposed OSTBC MIMO-OFDM systems

II. DERIVATION OF 2D-MMSE

Let us consider the pilot pattern of the proposed OSTBC MIMO-OFDM system, as shown in Figure 1. The pilot matrix $\mathbf{Y}_n(m) \in \mathbb{C}^{N_R \times N_c}$ received in the n th transmission block (TB) and the m th subcarrier is given by

$$\mathbf{Y}_n(m) = \mathbf{H}_n(m)\mathbf{X}_n(m) + \mathbf{W}_n(m), \quad (1)$$

where $\mathbf{H}_n(m) \in \mathbb{C}^{N_R \times N_T}$ and $\mathbf{X}_n(m) \in \mathbb{C}^{N_T \times N_c}$ denote the MIMO CFR and the OSTBC pilot codeword, respectively, and $\mathbf{W}_n(m) \in \mathbb{C}^{N_R \times N_c}$ denotes the AWGN matrix. Note that an OSTBC pilot codeword $\mathbf{X}_n(m)$ is comprised of N_c time slots. The vectorized system model corresponding to (1) is obtained as

$$\begin{aligned} \mathbf{y}_n(m) &= \text{vec}(\mathbf{Y}_n(m)) \\ &= \underbrace{(\mathbf{X}_n^T(m) \otimes \mathbf{I}_{N_R})}_{\Phi_n(m) \in \mathbb{C}^{(N_R N_c) \times (N_R N_T)}} \mathbf{h}_n(m) + \mathbf{w}_n(m), \end{aligned} \quad (2)$$

where $\mathbf{h}_n(m) = \text{vec}[\mathbf{H}_n(m)] \in \mathbb{C}^{(N_R N_T) \times 1}$ denotes the vectorized CFR and $\mathbf{w}_n(m) = \text{vec}[\mathbf{W}_n(m)]$. Let $\{k_1, k_2, \dots, k_{N_P}\}$ denote the set of indices of the pilot subcarriers. The channel estimation model for the n th TB is obtained by stacking all the pilot outputs as

$$\underbrace{\begin{bmatrix} \mathbf{y}_n(k_1) \\ \mathbf{y}_n(k_2) \\ \vdots \\ \mathbf{y}_n(k_{N_P}) \end{bmatrix}}_{\mathbf{y}_n \in \mathbb{C}^{(N_R N_c N_P) \times 1}} = \underbrace{\begin{bmatrix} \Phi_n(k_1) & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & \Phi_n(k_2) & \dots & \mathbf{0} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{0} & \mathbf{0} & \dots & \Phi_n(k_{N_P}) \end{bmatrix}}_{\Phi_n} \underbrace{\begin{bmatrix} \mathbf{h}_n(k_1) \\ \mathbf{h}_n(k_2) \\ \vdots \\ \mathbf{h}_n(k_{N_P}) \end{bmatrix}}_{\mathbf{h}_n \in \mathbb{C}^{(N_R N_T N_P) \times 1}} + \underbrace{\begin{bmatrix} \mathbf{w}_n(k_1) \\ \mathbf{w}_n(k_2) \\ \vdots \\ \mathbf{w}_n(k_{N_P}) \end{bmatrix}}_{\mathbf{w}_n},$$

$$\Rightarrow \mathbf{y}_n = \Phi_n \mathbf{h}_n + \mathbf{w}_n. \quad (3)$$

Furthermore, stacking $\mathbf{y}_n, \forall 1 \leq n \leq R$, the equivalent pilot-based channel estimation model corresponding to all the R TBs is obtained as

$$\underbrace{\begin{bmatrix} \mathbf{y}_1 \\ \mathbf{y}_2 \\ \vdots \\ \mathbf{y}_R \end{bmatrix}}_{\mathbf{y} \in \mathbb{C}^{(N_R N_c N_P R) \times 1}} = \underbrace{\begin{bmatrix} \Phi_1 & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & \Phi_2 & \dots & \mathbf{0} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{0} & \mathbf{0} & \dots & \Phi_R \end{bmatrix}}_{\Phi} \underbrace{\begin{bmatrix} \mathbf{h}_1 \\ \mathbf{h}_2 \\ \vdots \\ \mathbf{h}_R \end{bmatrix}}_{\mathbf{h} \in \mathbb{C}^{(N_R N_T N_P R) \times 1}} + \underbrace{\begin{bmatrix} \mathbf{w}_1 \\ \mathbf{w}_2 \\ \vdots \\ \mathbf{w}_R \end{bmatrix}}_{\mathbf{w}},$$

$$\Rightarrow \mathbf{y} = \Phi \mathbf{h} + \mathbf{w}. \quad (4)$$

Let the vectorized CFR $\tilde{\mathbf{h}}_n \in \mathbb{C}^{(N_R N_T N) \times 1}$ corresponding to the pilot and data subcarrier locations in the n th TB be defined as

$$\tilde{\mathbf{h}}_n = [\mathbf{h}_n^T(1), \mathbf{h}_n^T(2), \dots, \mathbf{h}_n^T(N)]^T. \quad (5)$$

Similarly, the vectorized CFR $\tilde{\mathbf{h}} \in \mathbb{C}^{(N_R N_T N R) \times 1}$ corresponding to the pilot and data subcarrier locations for the entire estimation block can be defined as

$$\tilde{\mathbf{h}} = [\tilde{\mathbf{h}}_1^T, \tilde{\mathbf{h}}_2^T, \dots, \tilde{\mathbf{h}}_R^T]^T. \quad (6)$$

The 2D-MMSE estimate of the overall CFR $\tilde{\mathbf{h}}$ is obtained as [1]

$$\hat{\tilde{\mathbf{h}}} = \mathbf{C} \mathbf{y}, \quad (7)$$

where $\mathbf{C} \in \mathbb{C}^{(N_R N_T N_R) \times (N_R N_c N_P R)}$ denotes the linear estimation matrix. By exploiting the orthogonality principle, we have:

$$\mathbb{E} \left[\left(\hat{\mathbf{h}} - \tilde{\mathbf{h}} \right) \mathbf{y}^H \right] = \mathbb{E} \left[\left(\mathbf{C} \mathbf{y} - \tilde{\mathbf{h}} \right) \mathbf{y}^H \right] = \mathbf{0}, \quad (8)$$

which derives the estimation matrix \mathbf{C} as

$$\mathbf{C} = \mathbf{R}_{\tilde{\mathbf{h}}\mathbf{y}} \mathbf{R}_{\mathbf{y}\mathbf{y}}^{-1}, \quad (9)$$

where $\mathbf{R}_{\mathbf{y}\mathbf{y}} = \mathbb{E} [\mathbf{y}\mathbf{y}^H] \in \mathbb{C}^{(N_R N_c N_P R) \times (N_R N_c N_P R)}$ denotes the auto-correlation matrix of the received pilot output \mathbf{y} and $\mathbf{R}_{\tilde{\mathbf{h}}\mathbf{y}} = \mathbb{E} [\tilde{\mathbf{h}}\mathbf{y}^H] \in \mathbb{C}^{(N_R N_T N_R) \times (N_R N_c N_P R)}$ represents the cross-correlation matrix of the CFR vector $\tilde{\mathbf{h}}$ and the received pilot output \mathbf{y} . Using the notations above, the 2D-MMSE estimate is derived as

$$\hat{\mathbf{h}} = \mathbf{R}_{\tilde{\mathbf{h}}\mathbf{y}} \mathbf{R}_{\mathbf{y}\mathbf{y}}^{-1} \mathbf{y}. \quad (10)$$

Assuming the samples of the noise vector \mathbf{w} to be independent and identically distributed with power σ_w^2 , the auto-correlation matrix $\mathbf{R}_{\mathbf{y}\mathbf{y}}$ can be further simplified to

$$\begin{aligned} \mathbf{R}_{\mathbf{y}\mathbf{y}} &= \mathbb{E} [\mathbf{y}\mathbf{y}^H] \\ &= \Phi \mathbf{R}_{hh} \Phi^H + \sigma_w^2 \mathbf{I}, \end{aligned} \quad (11)$$

where $\mathbf{R}_{hh} = \mathbb{E} [\mathbf{h}\mathbf{h}^H] \in \mathbb{C}^{(N_R N_T N_P R) \times (N_R N_T N_P R)}$ denotes the auto-correlation matrix of the CFR vector \mathbf{h} . Similarly, the cross-correlation matrix $\mathbf{R}_{\tilde{\mathbf{h}}\mathbf{y}}$ can be obtained as

$$\begin{aligned} \mathbf{R}_{\tilde{\mathbf{h}}\mathbf{y}} &= \mathbb{E} [\tilde{\mathbf{h}}\mathbf{y}^H] \\ &= \mathbf{R}_{\tilde{\mathbf{h}}h} \Phi^H, \end{aligned} \quad (12)$$

where the matrix $\mathbf{R}_{\tilde{\mathbf{h}}h} = \mathbb{E} [\tilde{\mathbf{h}}\mathbf{h}^H] \in \mathbb{C}^{(N_R N_T N_R) \times (N_R N_T N_P R)}$ denotes the crosscorrelation of the CFR vectors $\tilde{\mathbf{h}}$ and \mathbf{h} . The correlation matrix \mathbf{R}_{hh} can be derived as follows.

The CFR vector \mathbf{h} can be written in terms of its composite vectors $\mathbf{h}_n(k_i)$, $1 \leq n \leq R$, $1 \leq i \leq N_P$, as

$$\mathbf{h} = [\mathbf{h}_1^T(k_1) \dots \mathbf{h}_1^T(k_{N_P}) \mathbf{h}_2^T(k_1) \dots \mathbf{h}_2^T(k_{N_P}) \dots \mathbf{h}_R^T(k_1) \dots \mathbf{h}_R^T(k_{N_P})]. \quad (13)$$

Thus, the auto-correlation matrix $\mathbf{R}_{hh} = \mathbb{E} [\mathbf{h}\mathbf{h}^H]$ can be computed from each component correlation matrix $\mathbf{R}_{h,n_1,k_i,n_2,k_j} \in \mathbb{C}^{(N_R N_T) \times (N_R N_T)}$ defined as

$$\mathbf{R}_{h,n_1,k_i,n_2,k_j} = \mathbb{E} [\mathbf{h}_{n_1}(k_i) \mathbf{h}_{n_2}^H(k_j)]. \quad (14)$$

Similarly, the quantity $\mathbf{R}_{h,n_1,k_i,n_2,k_j}$ can also be used to compute the crosscorrelation matrix $\mathbf{R}_{\tilde{h}h} = \mathbb{E} [\tilde{\mathbf{h}}\mathbf{h}^H]$. The matrix $\mathbf{R}_{h,n_1,k_i,n_2,k_j}$ is evaluated next using the power delay profile of the L -tap channel and the associated AR-1 model.

Let $\bar{\mathbf{H}}_{n_1}(l) \in \mathbb{C}^{N_R \times N_T}$ denote the time-domain l th MIMO channel tap in TB n_1 . The associated CFR matrix $\mathbf{H}_{n_1}(k_i)$, which corresponds to the subcarrier index k_i in TB n_1 , can be expressed as

$$\mathbf{H}_{n_1}(k_i) = \underbrace{[\bar{\mathbf{H}}_{n_1}(0) \ \bar{\mathbf{H}}_{n_1}(1) \ \dots \ \bar{\mathbf{H}}_{n_1}(L-1)]}_{\bar{\mathbf{H}}_{n_1} \in \mathbb{C}^{N_R \times (LN_T)}} (\mathbf{f}_{k_i} \otimes \mathbf{I}_{N_T}), \quad (15)$$

where the truncated Fourier vector obeys $\mathbf{f}_{k_i} = [1, e^{-j\frac{2\pi k_i}{N}}, \dots, e^{-j\frac{2\pi(L-1)k_i}{N}}]^T \in \mathbb{C}^{L \times 1}$. Defining the vectorized CIR as $\bar{\mathbf{h}}_{n_1} = \text{vec}(\bar{\mathbf{H}}_{n_1}) \in \mathbb{C}^{(LN_R N_T) \times 1}$, the relationship between the vectorized CFR $\mathbf{h}_{n_1}(k_i)$ and $\bar{\mathbf{h}}_{n_1}$ can be obtained as

$$\begin{aligned} \mathbf{h}_{n_1}(k_i) &= \text{vec}[\mathbf{H}_{n_1}(k_i)] \\ &= \mathbf{F}_{k_i} \bar{\mathbf{h}}_{n_1}, \end{aligned} \quad (16)$$

where $\mathbf{F}_{k_i} = [\mathbf{f}_{k_i}^T \otimes \mathbf{I}_{N_R N_T}]$. Let $\bar{\mathbf{h}}_{n_1}(l) = \text{vec}(\bar{\mathbf{H}}_{n_1}(l))$ denote the vectorized l th tap and σ_l^2 denote the average power of each element of $\bar{\mathbf{h}}_{n_1}(l)$. This implies that $\mathbb{E} [\bar{\mathbf{h}}_{n_1}(l) \bar{\mathbf{h}}_{n_1}^H(l)] = \sigma_l^2 \mathbf{I}_{N_R N_T}$. Furthermore, the auto-correlation of the vectorized CIR $\bar{\mathbf{h}}_{n_1} = [\bar{\mathbf{h}}_{n_1}^T(0), \bar{\mathbf{h}}_{n_1}^T(1), \dots, \bar{\mathbf{h}}_{n_1}^T(L-1)]^T$, is derived as

$$\mathbb{E} [\bar{\mathbf{h}}_{n_1} \bar{\mathbf{h}}_{n_1}^H] = \begin{bmatrix} \sigma_1^2 \mathbf{I}_{N_R N_T} & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & \sigma_2^2 \mathbf{I}_{N_R N_T} & \dots & \mathbf{0} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{0} & \mathbf{0} & \dots & \sigma_{L-1}^2 \mathbf{I}_{N_R N_T} \end{bmatrix} = (\mathbf{P} \otimes \mathbf{I}_{N_R N_T}), \quad (17)$$

where the matrix $\mathbf{P} \in \mathbb{R}^{L \times L}$ is a diagonal matrix comprised of the average power $\{\sigma_l^2\}_{l=0}^{L-1}$ on its main diagonal. Furthermore, following the AR-1 model for the time-domain evolution of the channel, which is given as

$$\bar{\mathbf{h}}_n = \rho \bar{\mathbf{h}}_{n-1} + \sqrt{1 - \rho^2} \bar{\mathbf{v}}_n, \quad (18)$$

one can also derive the cross-correlation $\mathbb{E} [\bar{\mathbf{h}}_{n_1} \bar{\mathbf{h}}_{n_2}^H]$ as

$$\mathbb{E} [\bar{\mathbf{h}}_{n_1} \bar{\mathbf{h}}_{n_2}^H] = \rho^{|n_1 - n_2|} (\mathbf{P} \otimes \mathbf{I}_{N_R N_T}). \quad (19)$$

Using the results from (16) and (19), the cross-correlation matrix $\mathbf{R}_{h,n_1,k_i,n_2,k_j}$ of the vectorized CFRs $\mathbf{h}_{n_1}(k_i)$ and $\mathbf{h}_{n_2}(k_j)$, as defined in (14), can be derived as

$$\begin{aligned}\mathbf{R}_{h,n_1,k_i,n_2,k_j} &= \mathbb{E} [\mathbf{h}_{n_1}(k_i)\mathbf{h}_{n_2}^H(k_j)] \\ &= \mathbf{F}_{k_i} \mathbb{E} [\bar{\mathbf{h}}_{n_1} \bar{\mathbf{h}}_{n_2}^H] \mathbf{F}_{k_j}^H \\ &= \rho^{|n_1-n_2|} \mathbf{F}_{k_i} (\mathbf{P} \otimes \mathbf{I}_{N_R N_T}) \mathbf{F}_{k_j}^H.\end{aligned}\quad (20)$$

Using the result derived in (20), the closed-form expressions of \mathbf{R}_{hh} and $\mathbf{R}_{\tilde{h}h}$ can be evaluated as below. The auto-correlation matrix \mathbf{R}_{hh} can be derived as

$$\mathbf{R}_{hh} = \mathbf{J}_\rho \otimes (\mathbf{F} \tilde{\mathbf{P}} \mathbf{F}^H), \quad (21)$$

where we have $\tilde{\mathbf{P}} = (\mathbf{P} \otimes \mathbf{I}_{N_R N_T})$. The matrices \mathbf{J}_ρ and \mathbf{F} are defined as

$$\mathbf{J}_\rho = \begin{bmatrix} 1 & \rho & \dots & \rho^{R-1} \\ \rho & 1 & \dots & \rho^{R-2} \\ \vdots & \vdots & & \vdots \\ \rho^{R-1} & \rho^{R-2} & \dots & 1 \end{bmatrix}, \quad \mathbf{F} = \begin{bmatrix} \mathbf{F}_{k_1} \\ \mathbf{F}_{k_2} \\ \vdots \\ \mathbf{F}_{k_{N_P}} \end{bmatrix}. \quad (22)$$

Similarly, the cross-correlation matrix $\mathbf{R}_{\tilde{h}h}$ can be written as

$$\mathbf{R}_{\tilde{h}h} = \mathbf{J}_\rho \otimes (\bar{\mathbf{F}} \tilde{\mathbf{P}} \mathbf{F}^H), \quad (23)$$

where the matrix $\bar{\mathbf{F}}$ is defined as

$$\bar{\mathbf{F}} = \begin{bmatrix} \mathbf{F}_1 \\ \mathbf{F}_2 \\ \vdots \\ \mathbf{F}_N \end{bmatrix}. \quad (24)$$

Finally, the 2D-MMSE estimate is obtained as

$$\begin{aligned}\hat{\mathbf{h}} &= \mathbf{R}_{\tilde{h}h} \Phi^H (\Phi \mathbf{R}_{hh} \Phi^H + \sigma_w^2 \mathbf{I})^{-1} \mathbf{y} \\ &= \left(\mathbf{J}_\rho \otimes (\bar{\mathbf{F}} \tilde{\mathbf{P}} \mathbf{F}^H) \right) \Phi^H \left(\Phi \left(\mathbf{J}_\rho \otimes (\mathbf{F} \tilde{\mathbf{P}} \mathbf{F}^H) \right) \Phi^H + \sigma_w^2 \mathbf{I} \right)^{-1} \mathbf{y}.\end{aligned}\quad (25)$$

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